

Technology, Inc.
335 Pioneer Way
Mt View, California 94041
(650) 526-1490 Fax (650) 526-1494
e-mail: sales@netchip.com
Internet: www.netchip.com

NET1080 USB TurboCONNECT PRELIMINARY SPECIFICATION

For Revision 2 IC

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Revision History

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0.2	April 22, 1999	New Updates
0.3	May 4, 1999	Register, Pin Changes
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NET1080 USB TurboCONNECT

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1 Highlights

1.1 Introduction

The NetChip USB TurboCONNECT provides a single chip solution for connecting two USB Hosts. No external microprocessor is needed. The Netchip USB TurboCONNECT offers a quick and easy solution for host-to-host communications at speed equivalent to an Ethernet 10BT connection. Users can now network two or more Universal Serial Bus (USB) computers through standard Plug & Play technology without adding network cards.

1.2 Features

1.2.1 General Features

- Single-Chip USB Host-to-Host Connection
- Low Power CMOS in 48-pin PQFP Package
- Supports 100 mA low power USB Specification
- Supports 500 µA suspend current USB Specification
- 6 MHz crystal oscillator with internal PLL.
- MicroWire TM EEPROM interface
- Data transfer rate of 5 Mbps or greater
- 256 Byte FIFO per direction for data transfer
- Automatic retry of failed packets
- Low latency packet forwarding (minimum of 2.6 microseconds)

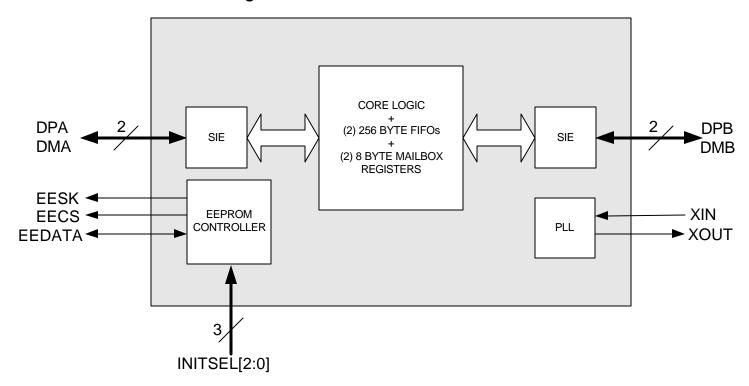
1.2.2 USB Features

- USB Specification Version 1.1 Compliant
- Supports Full-Speed USB Bandwidth of 12 Mbps
- Status Reporting through USB Interrupt Endpoints

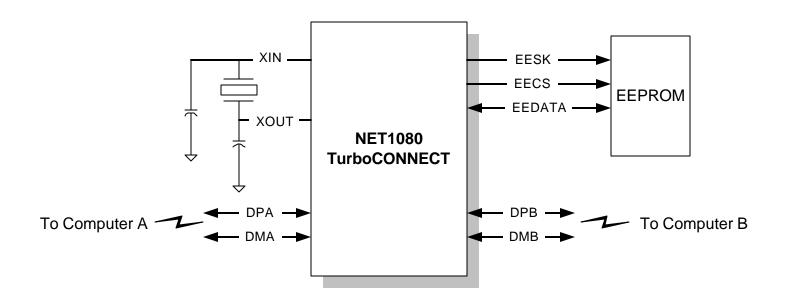
1.3 Overview

The NET1080 USB TurboCONNECT allows two Hosts to communicate with each other simultaneously. It consists of two SIEs to interface to two Hosts, bi-directional FIFOs, and an EEPROM interface. The EEPROM interface is provided to initialize the NET1080 with parameters necessary for enumeration of the device. Parameters loaded from the serial device include the Manufacturer ID, Product ID, Revision Number, Maximum Power fields, and USB control bits, as well as optional string descriptors. For maximum data throughput, the NET1080 provides a 256 byte FIFO per direction for data transfer. Other endpoints that are provided are a pair of CONTROL endpoints that support the USB standard requests and vendor specific requests, a pair of status endpoints that report the number of bytes in the next available packet. The NET1080 has the capability to enter low-power suspend as required by the USB specification. When enabled, it can perform a device remote wakeup on either port when data becomes available.

1.4 NET1080 Block Diagram



1.5 NET1080 System Block Diagram

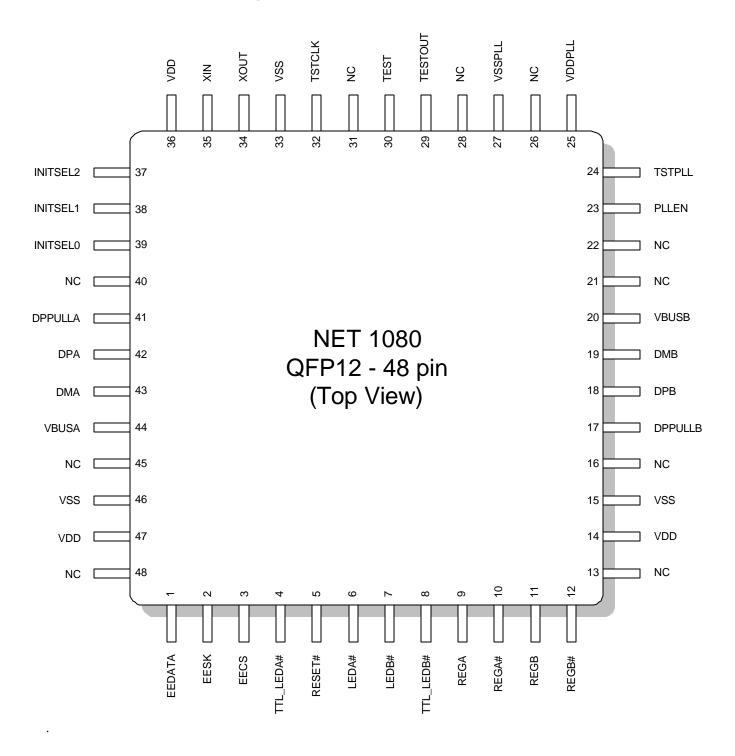


Changes from Rev 1 to Rev 2

The following changes were made to the NET1080 from Revision 1 to Revision 2:

- 1. Power Control: Revision 1 derives power only from the A port if both ports are powered. Revision 2 derives power from both ports unless one port is suspended, in which case it derives power from the other port.
- 2. OUT NAKs when other port is disconnected (erratum 630-0102-0103): Revision 1 NAKs OUT packets if the other port is disconnected causing packets to back up in the host driver. Revision 2 accepts (ACKs) packets if the other side is disconnected, but silently discards the packets.
- 3. Fixed Get Status failures on endpoints 1, 2, 82, and 83 (erratum 630-0102-0101).
- 4. Fixed Non-endpoint 0 traffic interfering with control protocol (erratum 630-0102-0102).
- 5. Changed LED algorithm to flash on for 255 milliseconds when CONFIGURED, and flash on for 32 milliseconds when data is transferred to the other port.
- 6. Added TTL_LED for each port. TTL_LED flashes on for 32 milliseconds whenever a packet on the port is discarded due to Time-To-Live expiration.

2 Pin Connection Diagram



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3 Pin Description

3.1 Table 3-1: Pin Types

Pin Type	Description	
I	Input	
О	Output	
I/O	Bi-Directional (with Tri-State)	
S	Schmitt Trigger	
TS	Tri-State	
TP	Totem Pole	
OD	Open Drain	
PD1	50KΩ Internal Pull-Down Resistor	
PU1	50KΩ Internal Pull-Up Resistor	
PD2	100KΩ Internal Pull-Down Resistor	
PU2	100KΩ Internal Pull-Up Resistor	
#	Active Low	

3.2 Table 3-2: Pin Descriptions

Signal Name	Pin	Туре	Description
EECS (MicroWire)	3	O, TP, 2mA	EEPROM Chip Select
EESK (MicroWire)	2	O, TP, 2mA	EEPROM Clock
EEDATA (MicroWire)	1	I/O, TS, S, 2mA, PU2	EEPROM Read/Write
INITSEL0	39	I	Initialization Select Bit 0. Select source of register initialization data.
INITSEL1	38	I	Initialization Select Bit 1. Select source of register initialization data.
INITSEL2	37	I	Initialization Select Bit 2. Select source of register initialization data. Bit 2 1 0 Source
RESET#	5	I, S, PU1	Reset. Connect to power-on reset.
DMA	43	I/O	USB Data Port A. DPA and DMA are differential data signals of the USB data port A. A 27 ohm series resistor between DMA and the USB connector is required to meet the USB impedance requirements.

	AA are differential data signals of the	
USB data port A. An external 1.5		
	5 K Ω resistor must be connected	
	pull-up resistor indicates to the Host	
	d device is connected to the USB. A	
27 ohm series resistor between D		
required to meet the USB impeda		
	IB are differential data signals of the	
	es resistor between DMB and the	
	et the USB impedance requirements.	
	AB are differential data signals of the	
	5 K Ω resistor must be connected from	
	p resistor indicates to the Host or	
	evice is connected to the USB. A 27	
	3 and the USB connector is required to	
meet the USB impedance require		
	g test purposes. Leave unconnected.	
TEST 30 I, PD1 Test Mode. Set to 0 or leave und		
XIN 35 I 6 MHz Oscillator Input. Conne		
•	nnect to 6 MHz. The oscillator stops	
when the USB Host suspends the		
	we unconnected if the internal PLL is	
	isabled, input an external 48 MHz	
signal.	S 4 4 0 1	
TSTPLL 24 I, PD1 PLL Test Enable. For manufaction unconnected.	turing test purposes. Set to 0 or leave	
	the internal PLL. Set to 0 to disable	
the internal PLL. In this case, an		
applied to the TSTCLK input.		
VBUSA 44 I, PD2 USB Port A power (+5V).		
VBUSB 20 I, PD2 USB Port A power (+5V).		
	output provides the VCC for the DPA	
	pull-up resister.	
	output provides the VCC for the DPB	
pull-up resister.	1 1	
LEDA# 6 O, TS, 12 mA, PU2 LED A Control. Active low out	tput to control the A host side LED.	
	tput to control the B host side LED.	
	Active low output to control the A	
host side TTL LED.	•	
TTL_LEDB# 8 O, TS, 12 mA, PU2 Time-To-Live LED B Control.	Active low output to control the B	
host side TTL LED.		
	nigh open drain output to control the	
A host side regulator.		
REGA# 10 O, TP, 6 mA Regulator A Control. Active lo	ow output to control the A host side	
regulator.	-	
	nigh open drain output to control the B	
host side regulator.	•	
	Regulator B Control. Active low output to control the B host side	
	-	
regulator.		
VDDPLL 25 Pwr PLL Supply Voltage. VDDPLL	z = 3.3V	

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VDD	14,36,47	Pwr	Supply Voltage. VDD = 3.3 volts.
VSS	15,33,47	Gnd	Ground.
NC	13, 16,		No Connect. Do not connect these pins.
	21, 22,		
	26, 28,		
	31, 40,		
	45, 48		

4 Functional Description

4.1 Start-Up

Before the NET1080 is ready to transfer data between two USB Hosts, a sequence of operations must occur involving the NET1080, the USB driver, and the TurboCONNECT drivers. First, the NET1080 reads required USB parameters from the external serial memory device. Next, the USB driver must enumerate the NET1080 on both sides. Finally, the TurboCONNECT driver configures the NET1080 with the correct parameters.

4.1.1 Reading from Initialization Device

When the NET1080 first comes out of a reset applied at its RESET# input, it reads various parameters required by the USB Host from an external serial memory. The NET1080 generates all signals necessary to read the data from the serial memory. Until this data is read, the NET1080 will respond to Host requests for a configuration descriptor or device descriptor with a NAK. If no valid serial memory device is installed, then the default values are used.

4.1.2 Enumeration and Configuration by the Host PC

USB defines a set of descriptor requests that are part of the enumeration process. The NET1080 responds to these requests automatically. When enumeration is complete, control of the NET1080 is passed to the TurboCONNECT driver.

As part of the enumeration process, the USB Host issues a Get Device Descriptor request. The NET1080 responds with the descriptor shown in section 7.1.4. Some of the values, such as the Manufacturer ID and Product ID, may come from the optional serial EEPROM. This Manufacturer ID and Product ID allow the Host to associate the manufacturer-supplied TurboCONNECT driver with the NET1080. The TurboCONNECT driver then finishes initializing the NET1080.

4.2 Initialization Interface

The NET1080 initialization must be completed before the NET1080 will respond to the Device Descriptor requests from the Host. The table below lists the different values of the INITSEL bits that are used to select various EEPROMs.

INITSEL	Source
0	MicroWire TM EEPROM (93CS06, 93CS46)
1	MicroWire TM EEPROM(93CS56, 93CS66)
2-7	Reserved

4.2.1 MicroWire EEPROMs

The NET1080 supports initialization and read/write operations to the following MicroWire EEPROMs:

- 93C06L 16 16-bit words (256 bits), CMOS, Low Voltage (2.7V to 4.5V)
- 93C46L 64 16-bit words (1 Kbits), CMOS, Low Voltage (2.7V to 4.5V)
- 93C56L 128 16-bit words (2 Kbits), CMOS, Low Voltage (2.7V to 4.5V)
- 93C66L 256 16-bit words (4 Kbits), CMOS, Low Voltage (2.7V to 4.5V)

Each of these devices has a 4-wire MicroWireTM serial interface. The NET1080 supports a 3-wire implementation of this interface in which the EEPROM DI pin is connected to the NET1080 EEDATA pin, and the EEPROM DO pin is connected to the EEPROM EEDI pin through a 33 ohm resistor.

After reset is inactive, the INITSEL bits are sampled to determine the source of the initialization information. If INITSEL[2:0] is 0 or 1, the NET1080 will determine if a non-blank MicroWire EEPROM is connected. If no EEPROM is detected, or the device is blank (first word is FFFF), then the default register values will be reported to the Host PC.

Otherwise, the following required fields from Table 3-1 below are loaded into the NET1080 from the EEPROM. These required fields are reported in the Device and Configuration descriptors during USB device enumeration. Information must be stored in the EEPROM as 16-bit words. For string descriptors, bits 7:0 of an EEPROM word are returned to the Host first, followed by bits 15:8.

Table 4-1: Required MicroWire Serial EEPROM Fields

Word Index	Contents	Default Value
0	Manufacturer ID . This field is reported to the Host PC in the USB device descriptor's "Manufacturer ID" field during enumeration.	0525h
1	Product ID . This field is reported to the Host PC in the USB device descriptor's "Product ID" field during enumeration.	1080h
2	Release Number. This field is reported to the Host PC in the USB device descriptor's "Release Number" field during enumeration.	0200h
3	Max Power. This field is reported to the Host PC in the USB configuration descriptor's "Max Power" field during enumeration. It is reported in units of 2mA. This field should reflect the maximum current drawn by the TurboCONNECT from the USB power pins.	0032h
4	USB Features. This field contains several control bits that are reported to the Host PC in the USB device descriptor and configuration descriptor. See USB Control Register for details.	
5	Interrupt Polling Rate. This field determines the rate at which the interrupt endpoints are polled by the Host.	
6 (bits 15:8)	Language ID String Start Index.	0000h
6 (bits 7:0)	Manufacturer String Start Index.	0000h
7 (bits 15:8)	Product String Start Index.	0000h
7 (bits 7:0)	Serial Number String Start Index.	0000h

In addition, if any "String Enable" fields are set in the **USB Control Register**, the fields in Table 4-2 must be defined.

Table 4-2: Additional MicroWire Serial EEPROM Fields for String Descriptors

Word Index	Contents
8-9h	Reserved. Write these words as a zero.
Ah-FFh	Available. This range of the serial EPROM is available for defining string descriptors.

If no string descriptors are used, the EEPROM image may be as short as 8 words (to provide the required fields to the Host PC). With string descriptors, the EEPROM can end at the end of the last string descriptor's definition. Since the string start index fields are only 8-bits, the beginning address of the last string in the EEPROM can't have a starting word address greater than 255.

The MicroWire EEPROMs can also be accessed from either Host using Vendor Specific commands to endpoint 0. Only one 16-bit word can be read or written for each Vendor Specific command. See sections 6.3 and 6.4.

For an EEPROM write, the Host issues a Vendor Specific Host to Device request to endpoint 0. The EEPROM word location is passed in the wIndex field of the Setup packet, and the 16-bit write data is passed in the wValue field of the Setup packet. Further attempts to access the EEPROM result in a NAK handshake until the write cycle has completed.

For an EEPROM read, the Host issues a Vendor Specific Device to Host request to endpoint 0. The EEPROM word location is passed in the wIndex field of the Setup packet. The associated IN tokens are NAKed until the data has been read from the EEPROM. A 2-byte packet containing the EEPROM read data is then returned to the host.

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4.3 USB Interface

The interface from the NET1080 to USB allows two Hosts to pass data between them. Each USB port on the NET1080 has the following endpoints.

4.3.1 Default Control Endpoint (Endpoint 00h)

Endpoint 0 is a bi-directional USB control endpoint which processes 8-byte packets to/from the Host PC. Each packet is decoded and USB control read and write 'requests' are handled automatically. Endpoint 0 supports the required USB protocol read and write requests (e.g. descriptor reads), as well as vendor-specific extensions. The vendor-specific extensions provide the capability to read and write internal registers.

4.3.2 Data OUT Endpoint (Endpoint 01h)

Endpoint 01h is a USB bulk OUT endpoint that accepts packets up to 64 bytes in length. Data received from a Host on this endpoint is transferred to a 256 byte FIFO that is connected to the Data IN Endpoint on the opposite USB port. When data is transferred to the other port, the LED for this port is turned on for a minimum of 32 milliseconds. Up to three complete packets can be in the FIFO at any time

4.3.3 Data IN Endpoint (Endpoint 81h)

Endpoint 81h is a USB bulk IN endpoint that transmits packets up to 64 bytes in length. In response to an IN token from the Host, data is read from a 256 byte FIFO that is connected to the Data OUT Endpoint on the opposite USB port, and is returned to the Host.

4.3.4 Mailbox OUT Endpoint (Endpoint 02h)

Endpoint 02h is a USB bulk OUT endpoint that accepts packets up to 16 bytes in length. Data received from a Host on this endpoint is transferred to an 8 byte IN Mailbox Endpoint on the opposite USB port. If the IN Mailbox of the other port is already busy, this endpoint returns a NAK handshake.

4.3.5 Mailbox IN Endpoint (Endpoint 82h)

Endpoint 82h is a USB interrupt IN endpoint that transmits the 8 bytes of IN Mailbox data. If no data is available, this endpoint returns a NAK handshake.

4.3.6 Status Endpoint (Endpoint 83h)

Endpoint 83h is a USB interrupt IN endpoint that reports the current number of bytes available in the next packet on the Data IN endpoint. If there are no packets available, the endpoint returns a NAK handshake. If there is a zero-length packet available, this endpoint returns 0.

4.4 Suspend Mode

When there is a three-millisecond period of inactivity on the USB, the USB specification requires a device to enter into a low-power suspended state. While in this state the device may not draw more than $500\,\mu\text{A}$ of current from the USB connector's power pins. To facilitate this, the NET1080 automatically enters the suspend state after detecting the three millisecond period of inactivity. The NET1080 goes into suspend after detecting the suspend condition on both USB ports. If only one port is suspended, the NET1080 draws power from the other port.

In the suspended state, the NET1080's oscillator shuts down, and most output pins are tri-stated to conserve power (see section 3, **Pin Description**).

If the host has enabled Device Remote Wakeup, the NET1080 will wake up the suspended host when there is data available on its Data IN endpoint The NET1080 leaves suspend mode when a Host initiated wake-up is detected.

4.5 Root Port Reset

If the SIE in the NET1080 detects a single-ended zero on the root port for greater than 2.5 microseconds, it is interpreted as a root port reset. The following resources are reset for that port:

- SIE
- USB state machines
- USB Address Register is set to 0

4.6 NET1080 Power Configuration

The USB specification defines both bus-powered and self-powered devices. A *bus-powered* device is a peripheral that derives all of its power from the upstream USB connector, while a *self-powered* device has an external power supply. The NET1080 is a low power bus-powered peripheral. It draws its power from either USB Port A or Port B, or both ports.

The USB specification specifies the following requirements for maximum current draw:

- A peripheral not configured by the Host may draw only 100 mA from the USB power pins.
- A configured low-power device may not draw more than 100 mA from the USB connector's power pins.
- In suspend mode, the peripheral may not draw more than 500 µA from the USB connector's power pins

The NET1080 meets all of these specifications. It is designed to be used as a bus-powered device.

5 Register Descriptions

The NET1080 contains a 16 x 16-bit local register space that can be accessed by either Host over USB using Ve ndor Specific commands to Endpoint 0. When the NET1080 receives a RESET signal from the RESET# pin or from a USB RESET command, the registers are set to their default values.

Writes to reserved registers are ignored, and reads from reserved registers return a value of 0. For compatibility with future revisions, unused bits within a register should always be written with a zero.

USB Register Description

These registers determine some of the values reported in USB device and configuration descriptors returned to the Hosts. The values in the registers may be changed by the initialization interface before a descriptor is returned to the Host. See Section 4.2.

5.1.1 USB Register Summary

Address	Register	Register Description	
Range			
0 h	MFGID	USB Manufacturer ID Field	
1 h	PRODID	Product ID Field	
2 h	RELNUM	Device release number	
3 h	MAXPWR	Maximum USB power used	
4 h	USBCTL	USB control	
5 h	INTPOLL	Interrupt Polling rate	
6 h	STRINDEX1	USB String Index 1 (Language ID, Manufacturer)	
7 h	STRINDEX2	USB String Index 2 (Product, Serial Number)	
8 h-F h	Reserved		
10 h	TTL	Time to Live	
11 h	STATUS	Status Register	
12 h-1E h	Reserved		
1F h	CHIPREV	Current Silicon Revision	

5.1.2 (Address 0h; MFGID) Manufacturer ID

Bits	Description	Read	Write	Default
				Value
15:0	USB Manufacturer ID. This register determines the Manufacturer ID during a 'Get	Yes	Yes	0525h
	Device Descriptor' request (assigned by USB-IF).			

5.1.3 (Address 1h; PRODID) Product ID

Bits	Description	Read	Write	Default Value
15:0	Product ID. This register determines the Product ID during a 'Get Device	Yes	Yes	1080h
	Descriptor' request.			

5.1.4 (Address 2h; RELNUM) Release Number

Bits	Description	Read	Write	Default Value
15:0	Release Number. This register determines the device release number during a 'Get	Yes	Yes	REL
	Device Descriptor' request.			NUM

Note: RELNUM is the silicon revision, encoded as a 4-digit BCD value. The value of RELNUM for the first release of the chip is 0100h. The least-significant two digits are incremented for mask changes, and the most-significant two digits increment for major revisions. This value can be changed by the EEPROM to implement an application release number.

5.1.5 (Address 3h; MAXPWR) Maximum Power

Bits	Description	Read	Write	Default Value
15:8	Reserved.	Yes	No	0
7:0	Maximum Power. This register determines the maximum USB power during a 'Get	Yes	Yes	32h
	Configuration Descriptor' request. Power is reported in units of 2 mA.			

5.1.6 (Address 4h; USBCTL) USB Control Register

Bits	Description	Read	Write	Default Value
15:13	Reserved	Yes	No	0
12	Language ID String Enable. If set, a language string ID is programmed into the EEPROM. The location of the language string is specified by the "Language String Start Index" byte in the serial EEPROM. If clear, the response to a Language ID String read is determined by the String Default Enable bit.	Yes	Yes	0
11	Manufacturer String Enable. If set, a manufacturer's string is programmed into the EEPROM. The location of the manufacturer's string is specified by the "Manufacturer String Start Index" byte in the serial EEPROM. If clear, the response to a Manufacturer String read is determined by the String Default Enable bit.	Yes	Yes	0
10	Product String Enable. If set, a product string is programmed into the EEPROM. The location of the product string in the EEPROM is specified by the "Product String Start Index" byte in the serial EEPROM. If clear, the response to a Product String language ID string read is determined by the String Default Enable bit.	Yes	Yes	0
9	Serial Number String Enable. If set, a serial number string is programmed into the EEPROM. The location of the serial number string is specified by the "Serial Number String Start Index" byte in the serial EEPROM. If clear, the response to a language ID string read is determined by the String Default Enable bit.	Yes	Yes	0
8	String Default Enable. If set, default strings are returned to the Host if the corresponding String Enable (bits 12:9) is 0. If clear, a string is returned only if the corresponding String Enable (bits 12:9) is 1.	No	Yes	1
7:4	Reserved	Yes	No	0
3	Flush Other. This bit flushes the Data IN FIFO for other port. This bit is self-clearing. When this bit is programmed from the EEPROM, it refers to the B port.	0	Yes/ Flush	0
2	Flush This. This bit flushes the Data IN FIFO for this port. This bit is self-clearing. When this bit is programmed from the EEPROM, it refers to the A port.	0	Yes/ Flush	0
1	Disconnect Other Port. Writing a 1 to this bit causes the DP Pull-up resistor not to be driven high, thus simulating a disconnect on the other USB Port. The port will stay disconnected until this bit is cleared. When programmed from the EEPROM, this bit refers to the B port.	Yes	Yes	0
0	Disconnect This Port. Writing a 1 to this bit causes the DP Pull-up resistor not to be driven high, thus simulating a disconnect on this USB Port. This bit clear itself after a 500-millisecond delay, and the port will automatically re-connect. When programmed from the EEPROM, this bit refers to the A port, and it will not clear itself after 500 milliseconds.	0	Yes	0

5.1.7 (Address 5h; INTPOLL) Interrupt Polling Interval Register

Bits	Description	Read	Write	Default
				Value
15:8	Interrupt Polling Interval Register for Endpoint 83h. This register specifies the	Yes	Yes	1
	interrupt polling interval in milliseconds for the Status Endpoint 83h. It is returned as the			
	last byte of the Status Endpoint descriptor when the Get Configuration Descriptor			
	request is issued.			

7:0	Interrupt Polling Interval Register for Endpoint 82h. This register specifies the	Yes	Yes	64h
	interrupt polling interval in milliseconds for the Mailbox Endpoint 82h. It is returned as			
	the last byte of the Mailbox Endpoint descriptor when the Get Configuration Descriptor			
	request is issued.			

5.1.8 (Address 6h; STRINDEX1) String Index 1

Bits	Description	Read	Write	Default
				Value
15:8	Language ID String Index. This field determines the EEPROM starting word address	Yes	Yes	0
	of the Language ID string.			
7:0	Manufacturer String Index. This field determines the EEPROM starting word address	Yes	Yes	0
	of the Manufacturer string.			

5.1.9 (Address 7h; STRINDEX2) String Index 2

Bits	Description	Read	Write	Default
				Value
15:8	Product String Index. This field determines the EEPROM starting word address of the	Yes	Yes	0
	Product string.			
7:0	Serial Number String Index. This field determines the EEPROM starting word address	Yes	Yes	0
	of the Serial Number string.			

5.1.10 (Address 10h; TTL) Time to Live

Bits	Description	Read	Write	Default Value
15:8	Time to Live Other Port. This field determines how many milliseconds a packet will	Yes	Yes	0
	stay in the Data FIFO on the other port before it is discarded. If set to 0, packets will			
	not be discarded.			
7:0	Time to Live This Port. This field determines how many milliseconds a packet will stay	Yes	Yes	0
	in the Data FIFO on this port before it is discarded. If set to 0, packets will not be			
	discarded.			

5.1.11 (Address 11h; STATUS) Status

Bits	Description	Read	Write	Default Value
15	Port A. This bit is set if read from the A port.	Yes	No	0
14	Connected Other Port. This bit indicates that the other side has connected	Yes	No	0
13	Suspended Other Port. This bit indicates that the other side has suspended.	Yes	No	0
12	Mailbox Data Available Other Port. This bit is set if there is data available in the USB Mailbox for the other port.	Yes	No	0
11:10	Reserved.	Yes	No	0
9:8	Packets Available Other Port. This field indicates the number of packets available in the Data FIFO of the other port.	Yes	No	0
7	Reserved.	Yes	No	1
6	Connected This Port. This bit indicates that this side has connected	Yes	No	0
5	Suspended This Port. This bit indicates that this side has suspended.	Yes	No	0
4	Mailbox Data Available This Port. This bit is set if there is data available in the USB Mailbox for this port.	Yes	No	0

3:2	Reserved.	Yes	No	0
1:0	Packets Available This Port. This field indicates the number of packets available in the	Yes	No	0
	Data FIFO of this port.			

5.1.12 (Address 1Fh; CHIPREV) NET1080 Silicon Revision

Bits	Description	Read	Write	Default Value
15:0	NET1080 Silicon Revision. This is the Silicon Revision Number for the NET1080	Yes	No	RELNUM

Note: RELNUM is the silicon revision, encoded as a 4-digit BCD value. The value of RELNUM for the first release of the chip is 0100h. The least-significant two digits are incremented for mask changes, and the most-significant two digits increment for major revisions. This value cannot be changed.

6 USB Vendor-Specific Device Requests (Endpoint 0)

Vendor specific requests to endpoint 0 are used to access the internal registers of the NET1080 and to perform read and write cycles to the EEPROM. For register and EEPROM accesses, the wIndex determine the address. A bRequest of 10h is used for register accesses, and a bRequest of 11h is used for EEPROM accesses.

6.1 Register Write

A vendor request to endpoint 0 is used to perform register writes. One 16-bit write can be performed for each transfer. The data is not written to the target register until it has been determined that the USB transfer was successful. The target register address is passed in bits 7:0 of the wIndex field of the Setup packet. The write data is passed in the wValue field of the Setup packet. If the wLength field is not 0, the endpoint will return a STALL handshake. The register is not actually written until the Status Phase of the vendor request has completed.

Setup Byte	Contents	Description	
0	BmRequestType	Bit 7 = direction (0=Out)	
		Bits 6:5 = type (2=vendor)	
		Bits $4:0 = $ Recipient $(0 = $ device $)$	
1	Brequest	10h = Register access	
2	wValue (LSB)	Write data (LSB)	
3	wValue (MSB)	Write data (MSB)	
4	wIndex (LSB)	Register Address	
5	wIndex (MSB)	Reserved – set to 0	
6	wLength (LSB)	VLength (LSB) Number of bytes in Data Phase – must be 0	
7	wLength (MSB)	Reserved – set to 0	

6.2 Register Read

A vendor request to endpoint 0 is used to perform register reads. One 16-bit read can be performed for each transfer. The target register address is passed in bits 7:0 of the wIndex field of the Setup packet. If the wLength field is not 2, the endpoint will return a stall acknowledge.

Setup Byte	Contents	Description	
0	BmRequestType	Bit 7 = direction (1=IN)	
		Bits 6:5 = type (2=vendor)	
		Bits $4:0 = $ Recipient $(0 = $ device $)$	
1	Brequest	10h = Register access	
2	wValue (LSB)	Reserved – set to 0	
3	wValue (MSB)	Reserved – set to 0	
4	wIndex (LSB)	Register Address	
5	wIndex (MSB)	Reserved – set to 0	
6	wLength (LSB)	Number of bytes to read, must be 2	
7	wLength (MSB)	Reserved – set to 0	

Following is a description of the contents of the IN packet associated with this control read transfer.

Byte Index	Contents
0	Register Read Data (LSB)
1	Register Read Data (MSB)

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6.3 EEPROM Write

A vendor request to endpoint 0 is used to perform EEPROM writes. One 16-bit write can be performed for each transfer. The EEPROM word address is passed in bits 9:0 of the wIndex field of the Setup packet. The write data is passed in the wValue field of the Setup packet. If the wLength field is not 0, the endpoint returns a STALL handshake. Further accesses to endpoint 0 are NAK'ed in the Status Phase until the write operation has completed.

Setup Byte	Contents	Description	
0	BmRequestType	Bit 7 = direction (0=Out)	
		Bits 6:5 = type (2=vendor)	
		Bits $4:0 = $ Recipient $(0 = $ device $)$	
1	Brequest	11h = EEPROM access	
2	wValue (LSB) Write data (LSB)		
3	wValue (MSB)	Write data (MSB)	
4	wIndex (LSB)	EEPROM word Address	
5	wIndex (MSB)	EEPROM word Address	
6	wLength (LSB) Number of bytes in Data Phase – must be 0		
7	wLength (MSB)	Reserved – set to 0	

6.4 EEPROM Read

A vendor request to endpoint 0 is used to perform EEPROM reads. One 16-bit read can be performed for each transfer. The EEPROM word address is passed in bits 9:0 of the wIndex field of the Setup packet. If the wLength field is not 2, the endpoint will return a stall acknowledge.

Setup Byte	Contents	Description	
0	BmRequestType	Bit 7 = direction (1=IN)	
		Bits 6:5 = type (2=vendor)	
		Bits $4:0 = $ Recipient $(0 = $ device $)$	
1	Brequest	11h = EEPROM access	
2	wValue (LSB)	Reserved – set to 0	
3	wValue (MSB)	Reserved – set to 0	
4	wIndex (LSB)	EEPROM word Address	
5	wIndex (MSB)	EEPROM word Address	
6	wLength (LSB)	Number of bytes to read, must be 2	
7	wLength (MSB)	Reserved – set to 0	

Following is a description of the contents of the IN packet associated with this control read transfer. IN tokens are NAK'ed until two bytes have been read from the EEPROM.

Byte Index	Contents	
0	EEPROM Read Data (LSB)	
1	EEPROM Read Data (MSB)	

6.5 Manufacturer Test Mode

A vendor specific request can be used to set or clear the Timing Test Mode bit. Timing Test Mode is used during silicon verification and should not be enabled during normal operation.

6.5.1 Device Clear Feature (Timing Test Mode)

Offset	Number of Bytes	Description	Default Value
	0	Clear the selected device feature wValue = 80h> Timing test mode (clears test bit) wIndex ignored wLength = 0	

6.5.2 Device Set Feature (Timing Test Mode)

Offset	Number of Bytes	Description	Default Value
	0	Set the selected device feature wValue = 80h> Timing test mode (sets test bit) wIndex ignored wLength = 0	

7 USB Standard Device Requests (Endpoint 0)

7.1 Control Read Transfers

7.1.1 Get Device Status

Offset	Number of Bytes	Description	Default Value
0	2	bits 15:2 = Reserved	0000h
		bit 1 = Device Remote Wakeup enabled	
		bit $0 = 0$	

7.1.2 Get Interface Status

Offset	Number of Bytes	Description	Default Value
0	2	bits 15:0 = Reserved	0000h

7.1.3 Get Endpoint 00h, 01h, 81h, 02h, 82h, 83h, 84h Status

Offset	Number of Bytes	Description	Default Value
0	2	bits 15:1 = Reserved	0000h
		bit $0 = \text{Endpoint}$ is stalled	

7.1.4 Get Device Descriptor (18 Bytes)

Offset	Number of Bytes	Description	Default Value
0	1	Length	12h
1	1	Type (device)	01h
2	2	USB Specification Release Number	0101h
4	1	Class Code	FFh (Vendor Specific)
5	1	Sub Class Code	00h
6	1	Protocol	00h
7	1	Maximum Endpoint 0 Packet Size	08h
8	2	USB Manufacturer ID	Value of MFGID register
10	2	Product ID	Value of PRODID register
12	2	Device Release Number	Value of RELNUM register
14	1	Index of string descriptor describing manufacturer	01h (if USBCTL Mfg. String
			Enable = 1)
			00h (if USBCTL Mfg. String
			Enable = 0)
15	1	Index of string descriptor describing product	02h (if USBCTL <i>Prod. String</i>
			Enable = 1)
			00h (if USBCTL <i>Prod. String</i>
			Enable = 0)
16	1	Index of string descriptor describing serial number	03h (if USBCTL Serial
			$Number\ String\ Enable=1)$
			00h (if USBCTL Serial
			$Number\ String\ Enable=0)$

7.1.5 Get Configuration Descriptor (53 bytes)

Note that all interface and endpoint descriptors are returned when this request is issued

Offset	Number of	Description	Default Value
~ ~	Bytes		
	ration Descrip		1
0	1	Length	09h
1	1	Type (configuration)	02h
2	2	Total length returned for this configuration	0035h
4	1	Number of Interfaces	01h
5	1	Number of this configuration	01h
6	1	Index of string descriptor describing this configuration	00h
7	1	Attributes	A0h
		bit 7 = Reserved – must be 1	
		bit 6 = Self-powered	
		bit 5 = Remote Wakeup capability	
		bits $4:0 = Reserved - set to 0$	
8	1	Maximum USB power required (in 2 mA units)	Value in MAXPWR
			register
Interfac	e 0 Descriptor	•	
0	1	Size of this descriptor in bytes	09h
1	1	Type (interface)	04h
2	1	Number of this interface	00h
3	1	Alternate Interface	00h
4	1	Number of endpoints used by this interface (excluding endpoint 0)	05h
5	1	Class Code	FFh (Vendor Specific)
6	1	Sub Class Code	00h
7	1	Device Protocol	00h
8	1	Index of string descriptor describing this interface	00h
	t 1 Descriptor		ı
0	1	Size of this descriptor	07h
1	1	Descriptor Type (endpoint)	05h
2	1	Endpoint Address	01h
_	_	bit 7 = direction (1 = IN, 0 = OUT)	
		bits 6:4 = reserved	
		bits 3:0 = endpoint number	
3	1	Endpoint Attributes	02h
		Bits 7:2 = reserved	
		Bits 1:0	
		00 = Control	
		01 = Isochronous	
		10 = Bulk	
		11 = Interrupt	
4	2	Maximum packet size of this endpoint	0040h
6	1	Interval for polling endpoint (not used)	00h

Endpo	oint 81h Desci	riptor	
0	1	Size of this descriptor	07h
1	1	Descriptor Type (endpoint)	05h
2	1	Endpoint Address	81h
-		bit 7 = direction (1 = IN, $0 = OUT$)	
		bits 6:4 = reserved	
		bits 3:0 = endpoint number	
3	1	Endpoint Attributes	02h
		bits 7:2 = reserved	0211
		bits 1:0	
		00 = Control	
		01 = Isochronous	
		10 = Bulk	
		11 = Interrupt	
4	2	Maximum packet size of this endpoint	0040h
6	1	Interval for polling endpoint (in ms)	00h
	oint 2 Descrip		OOII
_	1		07h
0	1	Size of this descriptor	
1	1	Descriptor Type (endpoint)	05h
2	1	Endpoint Address	02h
		bit 7 = direction (1 = IN, 0 = OUT)	
		bits 6:4 = reserved	
		bits 3:0 = endpoint number	
3	1	Endpoint Attributes	02h
		Bits $7:2 = reserved$	
		Bits 1:0	
		00 = Control	
		01 = Isochronous	
		10 = Bulk	
		11 = Interrupt	
4	2	Maximum packet size of this endpoint	0008h
6	1	Interval for polling endpoint (not used)	00h
Endpo	oint 82h Desci	riptor	
0	1	Size of this descriptor	07h
1	1	Descriptor Type (endpoint)	05h
2	1	Endpoint Address	82h
		bit $7 = \text{direction } (1 = \text{IN}, 0 = \text{OUT})$	
		bits 6:4 = reserved	
		bits 3:0 = endpoint number	
3	1	Endpoint Attributes	03h
		bits $7:2 = \text{reserved}$	
		bits 1:0	
		00 = Control	
		01 = Isochronous	
		10 = Bulk	
		11 = Interrupt	
4	2	Maximum packet size of this endpoint	0008h
6	1	Interval for polling endpoint (in ms)	Determined by bits 7:0 of
-	1	the tot poining endpoint (in this)	INTPOLL register
			IIII OIL ICEISICI

Endpo	Endpoint 83h Descriptor				
0	1	Size of this descriptor	07h		
1	1	Descriptor Type (endpoint)	05h		
2	1	Endpoint Address	83h		
		bit $7 = \text{direction} (1 = \text{IN}, 0 = \text{OUT})$			
		bits 6:4 = reserved			
		bits 3:0 = endpoint number			
3	1	Endpoint Attributes	03h		
		bits 7:2 = reserved			
		bits 1:0			
		00 = Control			
		01 = Isochronous			
		10 = Bulk			
		11 = Interrupt			
4	2	Maximum packet size of this endpoint	0001h		
6	1	Interval for polling endpoint (in ms)	Determined by bits 15:8		
			of INTPOLL register		

7.1.6 Get String Descriptor 0

Offset	Number of Bytes	Description	Default Value
0	4	Language ID (English = 09, U.S. = 04)	04h, 03h h0409

7.1.7 Get String Descriptor 1

Offset	Number of Bytes	Description	Default Value
0	38	Manufacturer Descriptor	26h, 03h "Netchip Technology"

7.1.8 Get String Descriptor 2

Offset	Number of	Description	Default Value
	Bytes		
0	48	Product Descriptor	30h, 03h
			"NET1080 USB
			TurboCONNECT"

7.1.9 Get String Descriptor 3

Offset	Number of Bytes	Description	Default Value
0	10	Serial Number Descriptor	0Ah, 03h "1001"

7.1.10 Get Configuration

Offset	Number of Bytes	Description	Default Value
0	1	Returns current device configuration	00h

7.1.11 Get Interface

Offset	Number of Bytes	Description	Default Value
0	1	Returns current alternate setting for the specified interface	00h

7.1.12 Set Address

Offset	Number of	Description	Default Value
	Bytes		
	0	Sets USB address of device	
		Value = device address, Index = 0	

7.2 Control Write Transfers

7.2.1 Set Configuration

Offset	Number of Bytes	Description	Default Value
	Dytes		
	0	Sets the device configuration	
		Value = Configuration value (0 or 1 supported),	

7.2.2 Set Interface

Offset	Number of Bytes	Description	Default Value
	0	Selects alternate setting for specified interface	
		Value = Alternate setting, Index = specified interface	

7.2.3 Device Clear Feature

Offset	Number of Bytes	Description	Default Value
	0	Clear the selected device feature	
		Value = feature selector	
		FS = 1> Device Remote Wakeup (disable)	

7.2.4 Device Set Feature

Offset	Number of Bytes	Description	Default Value
	0	Set the selected device feature	
		Value = feature selector	
		FS = 1> Device Remote Wakeup (enable)	

7.2.5 Endpoint Clear Feature

Offset	Number of Bytes	Description	Default Value
	0	Clear the selected endpoint feature	
		Value = feature selector, Index = endpoint number	
		FS = 0> Endpoint stall (clears stall bit)	

7.2.6 Endpoint Set Feature

Offset	Number of Bytes	Description	Default Value
	0	Set the selected endpoint feature	
		Value = feature selector, Index = endpoint number	
		FS = 0> Endpoint stall (sets stall bit)	

8 Bulk and Interrupt Endpoints

8.1 Endpoint 01h 'OUT' Transactions (Data Out Pipe)

Offset	Number of Bytes	Description	Default Value
	64	Host writes data to the FIFO connected to the Data IN	
		Pipe of the opposite USB port.	

8.2 Endpoint 81h 'IN' Transactions (Data In Pipe)

Offset	Number of	Description	Default Value
	Bytes		
	64	Host reads data from the FIFO connected to the Data IN	
		Pipe of this USB port.	

8.3 Endpoint 02h 'OUT' Transactions (Mailbox Out Pipe)

Offset	Number of Bytes	Description	Default Value
	8	Host writes data to the FIFO connected to the Mailbox	
		IN Pipe of the opposite USB port. If the IN Mailbox is	
		already busy, this endpoint returns a NAK handshake.	

8.4 Endpoint 82h 'IN' Transactions (Mailbox In Pipe)

Offset	Number of	Description	Default Value
	Bytes		
	8	Host reads data from the Mailbox IN Pipe of this USB	
		port using an interrupt IN transaction. If no bytes are	
		available in the Mailbox, this endpoint returns a NAK	
		handshake	

8.5 Endpoint 83h 'IN' Transactions (Status Input Pipe)

Offset	Number of	Description	Default Value
	Bytes		
	1	Host reads this endpoint using an interrupt IN	
		transaction. The value returned is the number of bytes	
		available in the Data IN endpoint. If no data is available,	
		this endpoint returns a NAK handshake. A value of 0	
		indicates a zero-length packet is available.	

9 Electrical Specifications

9.1 Absolute Maximum Ratings

Conditions that exceed the Absolute Maximum limits may destroy the device.

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{ m DD}$	Supply Voltage	With Respect to Ground	-0.3	4.0	V
V_{DDPLL}	PLL Supply Voltage	With Respect to Ground	-0.3	4.0	V
V_{I}	DC input voltage	With Respect to Ground	-0.3	$V_{\rm DD} + 0.5$	V
I_{OUT}	DC Output Current, per pin		-30	30	mA
T_{STG}	Storage Temperature	No bias	-65	150	° C
T_{AMB}	Ambient temperature	Under bias	-40	85	°C
V_{ESD}	ESD Rating	R = 1.5K, C = 100pF		2	KV

9.2 Recommended Operating Conditions

Conditions that exceed the Operating limits may cause the device to function incorrectly.

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DD}	Supply Voltage		3.0	3.6	V
V_{DDPLL}	PLL Supply Voltage		3.0	3.6	V
$V_{\rm I}$	Input Voltage		0	$V_{ m DD}$	V
T_A	Operating Temperature		0	70	° C
t_{R}	Input rise time		1	10	ns/V
$t_{\rm F}$	Input fall time		1	10	ns/V
Fosc	Oscillator or Crystal Frequency		5.985	6.015	MHz

9.3 DC Specifications

9.3.1 DC Specifications

Operating Conditions: V_{DD} : 3.3V \pm 5%, T_A = 0°C to 70°C All typical values are at V_{DD} = 3.3V and T_A = 25°C

Operating Conditions: Notes 1, 2.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I_{DD}	V _{DD} Supply Current	$V_{DD} = 3.3V$		30	45	mA
I_{DDS}	V _{DD} Supply Current (Suspend)	Device suspended		5	75	μΑ
V_{IH}	High Level Input Voltage		2.0			V
$V_{\rm IL}$	Low Level Input Voltage				0.8	V
${ m I}_{ m IL}$	Input Leakage Current	Any pin	-1		1	μΑ
I_{OZ}	Off State Leakage Current		-1		1	μΑ
$C_{I/O}$	Input or Output Pin Capactitance	Pin to GND			10	pF

9.3.2 USB Port DC Specifications

Operating Conditions: V_{DD} : 3.3V \pm 5%, T_A = 0°C to 70°C All typical values are at V_{DD} = 3.3V and T_A = 25°C

Operating Conditions: Notes 1,2.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{ m DI}$	Differential Input Sensitivity	(D+) - (D-)	0.2			V
V_{CM}	Differential Common Mode Range	Includes VDI range	0.8		2.5	V
V_{SE}	Single Ended Receiver Threshold		0.8		2.0	V
V_{OH}	Static Output High	R_L of 15 K Ω to GND	2.8		3.6	V
V_{OL}	Static Output Low	R_L of 1.5 K Ω to 3.6V			0.3	V
I_{LO}	Hi-Z State Data Line Leakage	$0V < V_{IN} < 3.3V$	-10		+10	μΑ
C_{IO}	I/O Capacitance	Pin to GND			20	pF

9.3.3 USB Port AC Specifications

Operating Conditions: V_{DD} : 3.3V \pm 5%, T_A = 0°C to 70°C All typical values are at V_{DD} = 3.3V and T_A = 25°C

Operating Conditions: Notes 1,2,3.

Symbol	Parameter	Conditions	Waveform	Min	Typ	Max	Unit
T_R	Rise & Fall Times	$C_L = 50 \text{ pF}$	Figure 9-1	4		20	ns
T_{F}		Notes 4,5		4		20	
T_{RFM}	Rise/Fall time matching	$(T_{R'}T_F)$	Figure 9-1	90		110	%
V_{CRS}	Output Signal Crossover Voltage			1.3		2.0	V
Z_{DRV}	Driver Output Resistance	Steady State Drive		10		15	Ω
T_{DRATE}	Data Rate			11.97	12	12.03	Mbs
T_{DDJ1}	Source Differential Driver Jitter to Next Transition	Notes 6,7.	Figure 9-2	-3.5	0	3.5	ns
T_{DDJ2}	Source Differential Driver Jitter for Paired Transitions	Notes 6,7	Figure 9-2	-4.0	0	4.0	ns
$T_{ m DEOP}$	Differential to EOP Transition Skew	Note 7	Figure 9-3	-2	0	5	ns
T_{EOPT}	Source EOP Width	Note 7	Figure 9-3	160	167	175	ns
T_{JR1}	Receiver Data Jitter Tolerance to Next Transition	Note 7	Figure 9-4	-18.5	0	18.5	ns
T_{JR2}	Receiver Data Jitter Tolerance for Paired Transitions	Note 7	Figure 9-4	-9	0	9	ns

T_{EOPR1}	EOP Width at Receiver; Must reject as EOP	Note 7	Figure 9-3	40		ns
T_{EOPR2}	EOP Width at Receiver; Must accept as EOP	Note 7	Figure 9-3	80		ns

9.3.4 USB Port AC/DC Specification Notes

- 1. All voltages measured from the local ground potential, unless otherwise specified.
- 2. All timings use a capacitive load (C_L) to ground of 50 pF, unless otherwise specified.
- 3. Full Speed timings have a 1.5 k Ω pull-up to 3.3 V on the D+ data line.
- 4. Measured from 10% to 90% of the data signal.
- 5. The rising and falling edges should be smoothly transitioning (monotonic).
- 6. Timing difference between the differential data signals.
- 7. Measured at crossover point of differential data signals.
- The maximum load specification is the maximum effective capacitive load allowed that meets the target hub V_{BUS} droop of 330 mV.

9.3.5 USB Port AC Waveforms

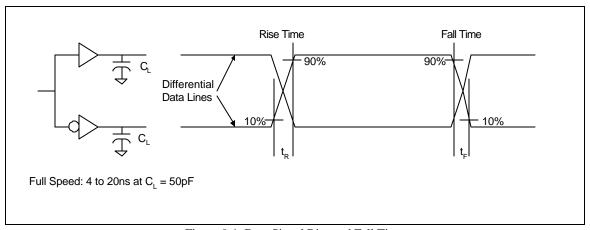


Figure 9-1. Data Signal Rise and Fall Time

T_{PERIOD}

Crossover

Points

Consecutive

Transitions

N*T PERIOD+TxJR1

Paired

Transitions

N*T PERIOD+TxJR2

Figure 9-2. Differential Data Jitter

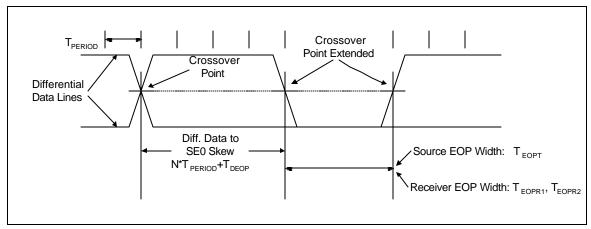


Figure 9-3. Differential to EOP Transition Skew and EOP Width

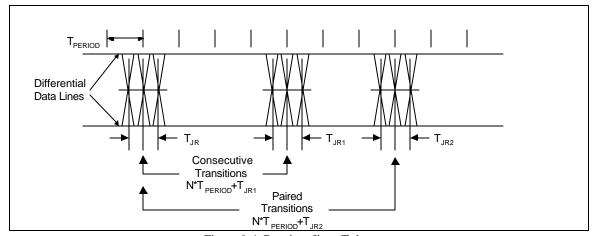
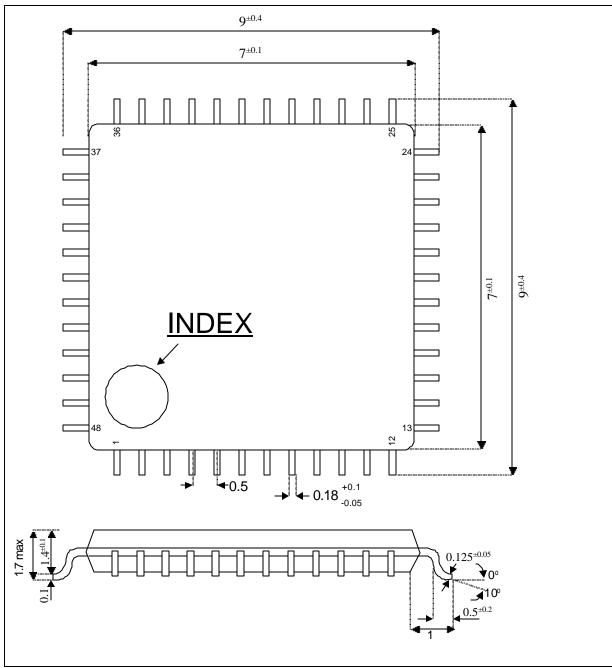


Figure 9-4. Receiver Jitter Tolerance

10 Mechanical Drawing



All dimensions in millimeters.